

1 Running head: Crossmodal action representations

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3 **Surface-based information mapping reveals crossmodal vision-action**
4 **representations in human parietal and occipitotemporal cortex**

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Abstract

Many lines of evidence point to a tight linkage between the perceptual and motoric representations of actions. Numerous demonstrations show how the visual perception of an action engages compatible activity in the observer’s motor system. This is seen for both intransitive actions (e.g. in the case of unconscious postural imitation) and for transitive actions (e.g. grasping an object). While the discovery of “mirror neurons” in macaques has inspired explanations of these processes in human action behaviours, the evidence for areas in the human brain that similarly form a crossmodal visual/motor representation of actions remains incomplete. To address this, in the present study, participants performed and observed hand actions while being scanned with fMRI. We took a data-driven approach by applying whole-brain information mapping using a multi-voxel pattern analysis (MVPA) classifier, performed on reconstructed representations of the cortical surface. The aim was to identify regions in which local voxel-wise patterns of activity can distinguish among different actions, across the visual and motor domains. Experiment 1 tested intransitive, meaningless hand movements, while Experiment 2 tested object-directed actions (all right-handed). Our analyses of both experiments revealed crossmodal action regions in the lateral occipitotemporal cortex (bilaterally) and in the left postcentral gyrus/anterior parietal cortex. Furthermore, in Experiment 2 we identified a gradient of bias in the patterns of information in the left hemisphere postcentral / parietal region. The postcentral gyrus carried more information about the effectors used to carry out the action (fingers vs whole hand), while anterior parietal regions carried more information about the goal of the action (lift vs punch). Taken together, these results provide evidence for common neural coding in these areas of the visual and motor aspects of actions, and demonstrate further how MVPA can contribute to our understanding of the nature of distributed neural representations.

54 **Introduction**

55 There is increasing evidence for a direct link between perception and action:
56 perceiving another person's action activates the same representations as does the
57 actual performance of the action. Such common codes between perceiving and
58 producing actions enable humans to embody the behavior of others and to infer the
59 internal states driving it (e.g., Barsalou et al. 2003). That is, by creating common
60 representations between ourselves and another person, we have a deeper
61 understanding of their current states, and are better able to predict their future
62 behaviour, facilitating complex social interactions. However, the basis of the brain's
63 crucial ability to relate one's own actions to those of others remains poorly
64 understood.

65 One possible contributing neural mechanism is found in macaque single-cell
66 studies of so-called "mirror neurons" (di Pellegrino et al. 1992), which have inspired
67 many theories of the neural basis of a range of human social processes such as theory
68 of mind, language, imitation, and empathy (Agnew et al. 2007; Corballis 2009;
69 Rizzolatti and Fabbri-Destro 2008). Surprisingly, given the extent of such theorizing,
70 the evidence for a human "mirror system" – that is, for brain areas in which the visual
71 and motor aspects of actions are represented in a common code -- is weak (Dinstein et
72 al. 2008b).

73 Numerous functional neuroimaging studies have identified brain regions that
74 are active during both the observation and the execution of actions (e.g. Etzel et al.
75 2008; Iacoboni et al. 1999). While these studies show spatial overlap of frontal and
76 parietal activations elicited by action observation and execution, they do not
77 demonstrate representational overlap between visual and motor action representations.
78 That is, spatially overlapping activations could reflect different neural populations in
79 the same broad brain regions (Gazzola and Keysers 2009; Morrison and Downing
80 2007; Peelen and Downing 2007b). Spatial overlap of activations per se cannot
81 establish whether the patterns of neural response are similar for a given action
82 (whether it is seen or performed) but different for different actions, an essential
83 property of the "mirror system" hypothesis.

84 Several recent studies have addressed this problem with fMRI-adaptation
85 designs (Grill-Spector and Malach, 2001). Dinstein et al. (2007) used this approach to
86 identify areas (such as the anterior intraparietal sulcus; aIPS) in which the BOLD
87 response was reduced when the same action was either seen or executed twice in a

88 row. However, none of the areas tested showed adaptation from perception to
89 performance of an action, or vice versa. Two subsequent studies revealed adaptation
90 from performance to observation (Chong et al. 2008), or vice versa (Lingnau et al.
91 2009), but neither showed bidirectional adaptation across the visual and motor
92 modalities. Most recently, Kilner et al. (2009), using a task that involved goal-
93 directed manual actions, showed adaptation effects bi-directionally in the inferior
94 frontal gyrus (superior parietal cortex was not measured).

95 Other recent studies have applied multi-voxel pattern analyses (MVPA;
96 Haynes and Rees 2006; Norman et al. 2006) of fMRI data to approach this problem.
97 For example, Dinstein et al. (2008a) found that patterns of activity in aIPS could
98 discriminate, within-modality, among three actions in either visual or motor
99 modalities. However, patterns of activity elicited by viewing actions could not
100 discriminate among performed actions (nor vice versa).

101 To summarize, neuroimaging studies to date using univariate methods do not
102 provide clear evidence for a brain area (or areas) in which a common neural code
103 represents actions across the visual and motor domains. Likewise, studies using
104 adaptation or MVPA methods also have produced limited and conflicting evidence.

105 In the present study, in order to identify brain areas in which local patterns of
106 brain activity could discriminate among these actions both within and across
107 modalities, we used MVPA. Unlike the previous MVPA studies reviewed above, each
108 participant's data were analyzed with a whole-cerebrum information mapping
109 ("searchlight") approach (Kriegeskorte et al. 2006). Furthermore, in contrast to the
110 volume-based approach used by most MVPA "searchlight" studies to date, we used
111 surface-based reconstructions of the cortex. This approach improves both the
112 classification accuracy and spatial specificity of the resulting information maps
113 (Oosterhof et al., in press). In this way, we were able to map brain areas that carry
114 crossmodal action representations, without restricting our analysis to pre-defined
115 regions of interest, and in a way that respects cortical anatomy.

116 Participants were scanned with fMRI while performing and viewing different
117 hand actions. In the first experiment, these were intransitive movements of the hand.
118 Participants viewed a short movie of one of three actions, and then repeatedly either
119 viewed or performed (with their own unseen hand) that action over the length of a
120 block. The aim of this first experiment was to use a simple stimulus set in order to test
121 our methods and to identify candidate visual/motor action representations. This was

122 followed by a second experiment, in which participants performed or viewed one of
123 four manual actions directed at an object. In this event-related experiment, the actions
124 defined a factorial design, in which either a lift or a punch goal was executed with
125 either the whole hand or with the thumb and index finger. We adopted this design
126 with two aims in mind: to encourage activity in the mirror system by testing actions
127 with object-directed goals (Rizzolatti and Sinigaglia, 2010); and to identify regions in
128 which the local pattern of activity more strongly represents action goals or action
129 effectors.

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Experiment 1

133 **Methods**

134 Subjects. Six right-handed, healthy adult volunteers (mean age 29; range = 24-
135 35; 1 female, 5 male) were recruited from the Bangor University community. All
136 participants had normal or corrected-to-normal vision. Participants satisfied all
137 requirements in volunteer screening and gave informed consent approved by the
138 School of Psychology at Bangor University. Participation was compensated at £30.

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Insert Figure 1 about here

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142 Design and procedure. Participants watched short movies (1.5 seconds, 60
143 frames/second) of simple hand actions, and also performed these actions in the
144 scanner. Supplementary Figure 1 shows the three actions used (labelled A, B, and C).
145 The data were collected across two sessions per subject. There were seven conditions
146 in the main experiment: do-A, do-B, do-C, see-A, see-B, see-C, and null (fixation)
147 trials. Each trial (Figure 1) started with a 500 msec blank screen followed by a 500
148 msec black rectangle, signifying the beginning of a new trial. For the null trials, a
149 black screen was presented for 24s. For the do and see trials, one of the three actions
150 (A, B, or C) was shown once, followed by an instruction on the screen (“see” or “do”)
151 for 2s. After an interval (3.5s), the movie was either repeated eight times (“see”
152 condition), or the participant performed the action eight times (“do” condition). To
153 match the “see” and “do” conditions temporally, a pulsating fixation dot was
154 presented in the middle of the screen during the “do” trials. This fixation dot was
155 presented from 8 until 24 seconds after trial onset and repeatedly changed size with a
156 phase of 2 seconds (large for 1.5 s, followed by small for 0.5 s). Participants were
157 instructed to execute the hand movements in time with the dot. Participants were not
158 able to see their own hand movements while in the scanner.

159

160 Each participant was scanned during two sessions, with 8 functional runs per
161 session. Within each of the two sessions, participants were scanned on two sets of
162 four runs, each one preceded by an anatomical scan. Each run started and ended with
163 a 16 s fixation period. The first trial in each run was a repeat of the last trial in the
164 previous run (in runs 1 and 5, it was a repeat of the last trial of runs 4 and 8,
165 respectively) and was not of interest (i.e. regressed out in the analysis; see below).
There were 14, 13, 13, and 13 remaining trials of interest (49 in total) for runs 1-4

166 (respectively), and similarly for runs 5-8. For each set of four runs, the seven
167 conditions were assigned randomly with the constraints that (1) each of the seven trial
168 conditions was preceded by each of the seven trial conditions exactly once, and (2)
169 each condition was present in each of the four runs at least once. Participants
170 completed 16 runs with (in total) $2 \times 2 \times 7 \times 6 = 168$ “do” and “see” trials of interest, that
171 is 28 trials for each action with each task.

172 To ensure that the actions were executed correctly, participants completed a
173 practice run of the experiment before going in the scanner. They were specifically
174 instructed not to move during “see” and null trials, and to move only their hand and
175 arm during “do” trials. They were told during training to use the viewed actions as a
176 model and to match these as closely as possible during their own performance.
177 Furthermore, we used an MR-compatible video camera (MRC Systems, Heidelberg,
178 Germany) to record participants’ hands throughout the scanning session to verify that
179 the actions were carried out correctly and that no movements were executed in the
180 “see” condition and null trials, or during the first 8s of a trial.

181 Data acquisition. The data were acquired using a 3T Philips MRI scanner with
182 a SENSE phased-array head coil. For functional imaging, a single shot echo planar
183 imaging sequence was used (T2*-weighted, gradient echo sequence; TR=2000 ms,
184 TE=35 ms; flip angle 90°) to achieve near-whole cerebrum coverage. The scanning
185 parameters were as follows: repetition time 2000 ms; 30 off-axial slices; slice pixel
186 dimensions $2 \times 2 \text{ mm}^2$; slice thickness 3 mm, no slice gap, FOV $224 \times 224 \text{ mm}^2$,
187 matrix 112×112 , phase encoding direction A-P, SENSE factor = 2. For participants
188 with large brains, where the entire cerebrum could not be covered, we gave priority to
189 covering the superior cortex (including the entire primary motor and somatosensory
190 areas and parietal cortex) at the expense of the inferior cortex (mainly temporal pole).
191 The frontal lobes were covered in all participants. Seven dummy volumes were
192 acquired before each functional run to reduce possible effects of T1 saturation.
193 Parameters for T1-weighted anatomical scans were: 288×232 matrix; 1 mm^3
194 isotropic voxels; TR=8.4 ms, TE= 3.8 ms; flip angle = 8° .

195 Volume preprocessing. Using AFNI (Cox 1996), for each participant and each
196 functional run separately, data was despiked (using AFNI’s 3dDespike with default
197 settings), time-slice corrected, and motion corrected (relative to the “reference
198 volume”: the first volume of the first functional run) with trilinear interpolation. The
199 percent signal change was computed by dividing each voxel’s time-course signal by

200 the mean signal over the run and multiplying the result by a hundred. The four
201 anatomical volumes were aligned with 3dAllineate, averaged, and aligned to the
202 reference volume (Saad et al. 2009).

203 Although we took measures to limit motion-related artifacts including data
204 “spikes” (e.g. by using short-trajectory hand movements, as far from the head as
205 possible) it is very likely that there were more movement artifacts in the “do” than
206 “see” trials. However, one benefit of the crossmodal analyses on which we focus our
207 attention is that such incidental uncontrolled differences between “see” and “do” trials
208 can only work against our hypothesis. That is, they will tend to reduce the similarity
209 between activity patterns elicited in the “see” and “do” conditions, and hence make it
210 more difficult for a classifier to discriminate among actions crossmodally.

211 Univariate volume analyses. A General Linear Model analysis was performed
212 using the AFNI 3dDeconvolve program in order to estimate the BOLD responses for
213 each do and see action trial (16 s each). Beta coefficients were estimated separately
214 for each of the do and see action trials by convolving a boxcar function (16 s on,
215 starting 8 s after trial onset) with the canonical hemodynamic response function
216 (HRF). The beta coefficients from the first trial in each run were not of interest (see
217 above), while beta coefficients from the other trials were used in the multi-voxel
218 pattern analysis (MVPA; see below). For each run, predictors of no interest were
219 included to regress out potential effects from the instruction part from each trial, also
220 by convolving a boxcar function (3.5 s on, starting 1.0 s after trial onset) with the
221 canonical HRF. To remove low frequency trends, predictors of no interest for
222 constant, linear, quadratic, and cubic trends were included in the model as well.

223 Surface preprocessing. For each participant and hemisphere, anatomical
224 surface meshes of the pial-grey matter (“pial”) and smoothed grey matter-white
225 matter (“white”) boundaries were reconstructed using Freesurfer (Fischl et al. 2001),
226 and these were used to generate an inflated and a spherical surface. Based on surface
227 curvature, the spherical surfaces of all participants were aligned to a standard
228 spherical surface (Fischl et al. 1999). Using AFNI’s MapIcosehedron, these spherical
229 surfaces were resampled to a standardized topology (an icosehedron in which each of
230 the twenty triangles is subdivided into 10,000 triangles), and the pial, white, and
231 inflated surfaces were then converted to the same topology. This ensured that each
232 node on the standardized surfaces represented a corresponding surface location across
233 participants; therefore, group analyses could be conducted using a node-by-node

234 analysis. The affine transformation from Freesurfer’s anatomical volume to the
235 aligned anatomical volume was estimated (using AFNI’s 3dAllineate) and applied to
236 the coordinates of the standardized pial and white surfaces to align them with the
237 reference volume.

238 For each participant, we also estimated the required affine transformation to
239 bring the anatomical volume into Talairach space (Talairach and Tournoux 1988), and
240 applied this transformation to the surfaces. The pial and white surfaces in Talairach
241 space were averaged to construct an intermediate surface, that was used to measure
242 distances (described below) and surface areas in a manner that was unbiased to the
243 participants brain size. To limit our analysis to the cortex, and to improve statistical
244 power when correcting for multiple comparisons, an exclusion mask covering the
245 subcortical medial structures was drawn on the group map. This mask was
246 subsequently used in the searchlight analyses.

247 Intra-participant surface-based “searchlight” multi-voxel pattern analyses. To
248 investigate which regions represent information about which of the three actions (A,
249 B, and C) was perceived or performed, we combined a searchlight (Kriegeskorte et al.
250 2006) with multi-voxel pattern analysis (MVPA; Haynes and Rees 2006; Norman et
251 al. 2006) implemented in Matlab® (the Mathworks Ltd., Cambridge, UK) using a
252 geodesic distance metric on the surface meshes (see Figure 2). For each participant
253 and hemisphere, in the intermediate surface a “center node” was chosen and all nodes
254 within a 12 mm radius circle on the surface (using a geodesic distance metric;
255 Kimmel and Sethian 1998) were selected using the Fast Marching Toolbox (Peyre
256 2008). For each selected node on the intermediate surface, a line was constructed that
257 connected the corresponding nodes on the standardized pial and white surfaces, and
258 on each line, ten equidistant points were constructed. The searchlight contained all
259 voxels that intersected at least one point from at least one line.

260

261 Insert Figure 2 about here

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263 Each selected voxel in the searchlight was associated with 168 beta estimates,
264 one from the final 16 s of each “do” or “see” trial of interest. These beta estimates
265 were partitioned into 56 chunks (2 modalities x 28 occurrences of each action), so that
266 each chunk contained three beta estimates of action A, B and C in that modality. To
267 account for possible main effect differences between modalities or specific trials, for

268 each voxel and chunk separately, the three beta estimates were centered by subtracting
269 the mean of three beta estimates.

270 Based on these centered responses, a multiclass Linear Discriminant Analysis
271 classifier was used to classify trials using 28-fold cross validation. Because typically
272 the number of voxels in selected regions was larger than the number of beta-estimates
273 from the GLM, the estimate of the covariance matrix is rank deficient. We therefore
274 regularized the matrix by adding the identity matrix scaled by one percent of the mean
275 of the diagonal elements. For each of the two modalities, the classifier was trained on
276 the beta estimates from 27 chunks in that modality, and tested on the remaining chunk
277 in the same modality (unimodal classification), and also tested on the corresponding
278 chunk in the other modality (crossmodal classification). This procedure was repeated
279 for all 28 chunks.

280 For each of the four combinations of train and test modality (train (“do”, “see”)
281 x test (“do”, “see”)), raw accuracies were computed by dividing the number of
282 correctly classified trials by the total number of trials. For statistical inference in the
283 group analysis (see below), raw accuracies were converted to z-scores based on their
284 binomial distribution under the null-hypothesis of chance accuracy (1/3). For the
285 crossmodal classification, accuracies from the two cross-modal classifications (train
286 on “see”, test on “do”; and vice versa) were combined before computing the z-score.
287 This procedure was repeated for all of the 100,002 nodes in the intermediate surface.
288 That is, each node was taken as the center of a circle and classification accuracy was
289 computed using the surrounding nodes within the selection radius.

290 Surface-based group analysis. A random effects analysis was used to find
291 regions where classification accuracy was above chance, by applying (for each node)
292 a t-test against the null hypothesis of zero mean of the accuracy z-score (i.e.
293 classification accuracy at chance level) and applying a node-wise threshold of $p=0.05$
294 (two-tailed). To find clusters that were significant while correcting for multiple
295 comparisons, we employed a bootstrap procedure (Nichols and Hayasaka 2003). For a
296 single bootstrap sample, we took six individual participant maps randomly (sampled
297 with replacement). For each of the six maps, the sign of the z-score was negated
298 randomly with probability of 50%, which is allowed under the null hypothesis of
299 chance accuracy (z-score of 0). We note that the data in the bootstrap sample is
300 unbiased with respect to the spatial autocorrelation structure in the original group
301 map. A t-test was conducted on the resulting six maps and the resulting map was

302 clustered with the same threshold as the original data. This procedure was repeated a
303 hundred times (i.e. we took a hundred bootstrap samples), and for each bootstrap
304 sample the maximum cluster extent (in mm²) across the surface was computed,
305 yielding a distribution of maximum cluster extent values under the null hypothesis of
306 chance accuracy. For each cluster in the original group results map, the α -level
307 (significance) was set at the number of times that the maximum cluster extent value
308 across bootstrap samples was larger than the observed cluster extent, divided by the
309 number of bootstrap samples (100). Clusters are only reported for which $\alpha \leq 0.05$. For
310 each cluster, its center-of-mass coordinates were computed by taking the average
311 coordinates of its nodes, relatively weighted by each node's area.
312

334 **Discussion**

335 Patterns of BOLD activity in the left anterior parietal cortex, and in lateral
336 occipitotemporal cortex bilaterally, carry information that can discriminate among
337 meaningless intransitive actions across the visual and motor domains. These findings
338 suggest that in these areas the distinguishing properties of actions are represented in a
339 distributed neural code, and that at least some aspects of this code are crossmodal.
340 That is, some features of the patterns that code the actions must be common across the
341 visual and motor modalities. Because the actions were meaningless and intransitive, it
342 is unlikely that these codes reflect action semantics, and the results of Experiment 1
343 could not have been driven by the features of a target object (cf. Lingnau et al. 2009).

344 The property of representing intransitive actions in a common vision/action
345 code may be functional in its own right, e.g. to support the learning of movements by
346 observation alone. Aside from explicit, intentional learning, there are several
347 demonstrations of what might be called social “contamination” effects – e.g.
348 situations in which an observer spontaneously adopts the postures or movements of
349 another individual. These automatic mirroring responses appear to facilitate social
350 interactions and social bonding (Chartrand and Bargh 1999; Van Baaren et al. 2003)
351 and may mediate interactive or collaborative actions. Additionally, crossmodal
352 intransitive representations may contribute to the understanding of object-directed
353 actions, for which the underlying movements may themselves be key elements.

354 Our analyses of unimodal information identified widespread areas that carried
355 weak but significantly above-chance information about either which action was
356 viewed or was performed. Importantly, in contrast to the critical crossmodal test, in
357 the unimodal analyses the stimulus (or motor act) was essentially identical across
358 training and test data sets. In such situations, MVPA can be a highly sensitive method,
359 potentially making use of many sources of congruency between the neural events
360 elicited by repeated instances of a given stimulus (and not necessarily the sources of
361 interest to the investigators) such as commonalities in motion (Kamitani and Tong
362 2006; Serences and Boynton 2007), thoughts (Stokes et al. 2009), intentions (Haynes
363 et al. 2007) or stimulus orientation (Kamitani and Tong 2005). This means that in
364 general, proper interpretation of an informative brain region requires control
365 conditions that test to what extent representations generalize. In the present study, this
366 is much less a concern in the crossmodal conditions, given the great differences at the

367 sensory / motor level between seeing an action and performing that action out of
368 view.

369 Because of the novelty of our methods and of some of the findings (e.g.
370 crossmodal action information in lateral occipitotemporal cortex) we set out to
371 replicate and extend the results of Experiment 1 before attempting to interpret them.
372 First, in order to extend our findings to goal-directed behaviours, in Experiment 2 we
373 tested transitive actions. It has been proposed that the “mirror” system is more
374 effectively engaged by object-directed actions (e.g., Rizzolatti et al. 1996a) and we
375 speculated that testing such actions could increase the recruitment of ventral premotor
376 cortex. Second, we adopted an event-related design. Although such a design carries
377 the risk of reducing statistical power, we reasoned that it would greatly increase
378 participants’ engagement in the task (compared to Experiment 1) by requiring more
379 frequent attention to task cues and more frequent switching between conditions.
380 Third, we tested more participants, which increases statistical power in the random
381 effects and bootstrap analyses. Finally, we introduced a monitoring task in the “see”
382 conditions, which required participants to attend actively to the viewed hand
383 movements, as compared to passive viewing, as in Experiment 1.

384 Beyond these largely methodological improvements, we introduced new
385 variables to the design of Experiment 2. We orthogonally varied two aspects of the
386 actions that were viewed and performed by participants. One factor concerned the
387 *effectors* used to make contact with the object during action execution. Half of the
388 actions involved the tips of the thumb and index finger, while the other half involved
389 the whole hand. Orthogonally, we manipulated action *goals*. Half of the actions
390 involved grasping and lifting an object on to a platform in front of the participant. The
391 other half of the actions required the participant to “punch” the side of the object so
392 that it leaned away from the participant before returning to the upright position. By
393 virtue of this factorial manipulation, we were able to test not only for brain regions in
394 which patterns carried crossmodal visuo-motor action representations, but also to
395 further test the nature of these representations (cf. similar efforts in extrastriate cortex,
396 e.g. Aguirre 2007; Haushofer et al. 2008; Op de Beeck et al. 2008). Specifically, we
397 tested whether a given area carries relatively more (crossmodal) information about the
398 effector used to manipulate the object or about the goal of actions on the object.

399 In Figure 4, we illustrate a simple scheme for thinking about how patterns of
400 cortical activity relate to different types of informational content in a given region.

401 The scheme centres on assessing the similarity of patterns elicited by particular
402 combinations of seen and performed actions in Experiment 2. (We note that the
403 matrices in Figures 4a-c are congruent with how accuracies were computed in
404 Experiment 1, but with three actions instead of four). Each row and each column (for
405 training set and test set, respectively) represents one of the eight conditions in the
406 experiment, formed by the combination of modality (see, do) x effector (finger, hand)
407 x goal (lift, punch). Where fMRI activity patterns are predicted to be similar (across
408 training and test set, for a given brain region and a given participant), a cell matrix is
409 marked with a pink square. Conversely, trials that were used in the cross-validation
410 scheme but where no similarity between patterns is predicted, are indicated with a
411 grey square. Different matrix arrangements illustrate predicted similarity patterns for
412 within-modality representations (Figure 4a,b), for a visual / motor crossmodal
413 representation (Figure 4c), and for representations biased in favour of either action
414 effectors or goals (Figures 4d,e,f).

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Insert Figure 4 about here

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Experiment 2

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419 **Methods**

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421 Subjects. 11 right-handed, healthy adult volunteers were recruited from the
422 Bangor University community. All participants had normal or corrected-to-normal
423 vision. Participants satisfied all requirements in volunteer screening and gave
424 informed consent approved by the School of Psychology at Bangor University.
425 Participation was compensated at £20.

426 Design and Procedure. Participants either performed or watched object-
427 directed actions in the scanner (Figure 5). The object was cup-shaped and attached
428 with an elastic string to a table located partially inside the scanner bore,
429 approximately above the navel of the participant (Figure 5a,b). Earphones delivered
430 auditory instructions to the participants, in the form of words spoken by Apple Mac
431 OS X 10.5 text-to-speech utility “say” using the voice of “Alex”. Participants could
432 see the table and the object through a forward-looking mirror mounted on the scanner
433 coil. An experimenter of the same gender as the participant (AJW or NNO) was
434 present in the scanner room to perform real-time actions on the object, which were
435 then observed by the participant through the mirror. Visual instructions for the
436 experimenter were projected on a wall in the scanner room, invisible to the
437 participant.

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441 The action instructions varied orthogonally on the effector used (“finger” for
442 thumb and index finger, or “hand” for the whole hand) and on the goal of the action
443 (“lift” to raise the object, or “punch” to push the object on its side). Thus, the
444 experimental design was 2 (modality: “do” vs. “see”) x 2 (effector: “finger” vs.
445 “hand”) x 2 (goal: “lift” vs. “punch”). Figure 5c shows the four actions, from the
446 approximate perspective of the participant while executed by the experimenter.

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450 There were nine conditions in the main experiment: eight for which an action
451 was seen or performed, and one null (no action) condition. Each trial (Figure 6)

452 started with an auditory instruction “close” (for “do” and null trials), or “open” (for
453 “see” trials). Participants were instructed to open or close their eyes according to the
454 instruction, and compliance was monitored using a scanner-compatible eye tracking
455 system. Simultaneously, a visual instruction was given to the experimenter to indicate
456 whether or not (s)he should perform an action. Two seconds after trial onset, for “do”
457 trials, another auditory instruction was given to the participant to indicate the specific
458 action to be executed, in the order goal-effector (e.g. “lift finger”, “punch hand”). For
459 “see” trials, no auditory instruction was given to the participant, but they had to
460 monitor the action executed by the experimenter. To ensure the attention of the
461 participant during these trials, occasionally (twice per run, on average) the
462 experimenter repeated the action twice in rapid succession (“catch trial”), and
463 participants were instructed to knock on the table to indicate that they had observed
464 such a repeat. For both “do” and “see” trials, the names of the action goal and effector
465 were presented visually to the experimenter: for “do” trials, so that (s)he could verify
466 that the participant executed the correct action, and for “see” trials, so that (s)he knew
467 which action to execute. Each trial lasted for seven seconds.

468 Each participant was scanned during a single session with eight functional (F)
469 runs and three anatomical (A) scans, in the order AFFF AFFF AFFF. For two
470 participants, only six functional runs could be acquired due to participant discomfort
471 and technical difficulties with the table-object attachment, respectively. First order
472 counterbalancing was achieved by partitioning the functional runs in (three or four)
473 sets of two runs each. For each set of two runs, the order of the conditions was
474 randomly assigned with the constraints that (1) each of the nine conditions was
475 preceded by each of the nine conditions exactly once, and (2) each condition was
476 present in each of the two runs four or five times. To reinstate potential carryover
477 effects from one trial the next at run boundaries, the first four and last four trials in a
478 run were a repeat of the last four and first four trials, respectively, of the other run in
479 the same set. The first two and last two trials in each run, trials during which
480 participants executed the wrong action, and catch trials were all marked as trials of no
481 interest and modelled separately in the General Linear Model (see below). The first
482 trial started two seconds after the beginning of the run.

483 Participants were instructed as follows: to rest their right hand on the table, on
484 the right-hand side of the object (from their perspective); to only move their right
485 hand during “do” trials; to leave enough space in between their hand and the object so

486 that the experimenter could execute the actions on the object without touching their
487 hand; to keep their left hand and arm under the table, out of view; and after a “close”
488 instruction, to keep their eyes closed until they were instructed to open them again. To
489 ensure that participants followed the instructions correctly, they completed two
490 practice runs of the experiment: the first before going in the scanner, the second in the
491 scanner during the first anatomical scan. Participants were told during training to use
492 the viewed actions as a model and to match these as closely as possible during their
493 own performance.

494 Data acquisition. The data were acquired as in Experiment 1, with a variation
495 in some of the scanning parameters for functional imaging: repetition time 2500 ms;
496 40 off-axial slices; 2.5 mm³ isotropic voxels, no slice gap, FOV 240 x 240 mm²,
497 matrix 96 x 96.

498 Univariate volume analyses. Volume preprocessing was identical to
499 Experiment 1, and univariate analyses very similar to Experiment 1 except for the
500 following. For each run separately, eight beta coefficients of interest (corresponding
501 to the four “do” and four “see” action conditions) were estimated with a General
502 Linear Model by convolving a boxcar function (3 s on, starting 2 s after trial onset)
503 with the canonical hemodynamic response function (HRF). Each trial of no interest
504 (see above) was regressed out with a separate regressor of the same shape. To remove
505 low frequency trends, predictors of no interest for constant, linear, quadratic, and
506 cubic trends were included in the model as well.

507 Intra-participant surface-based “searchlight” multi-voxel pattern analyses.
508 Before MVPA, surfaces were preprocessed as in Experiment 1. Surface-based MVPA
509 was also performed similarly to Experiment 1, with the only difference that the beta
510 estimates were partitioned in two chunks per run corresponding to the two modalities
511 (“do” and “see”), so that cross-validation was 8-fold for both unimodal and
512 crossmodal classification. In other words, data from one run was used to test the
513 classifier, while data from the other runs was used to train it. Based on the matrices in
514 Figure 4, accuracies were computed as follows. Trials for which the combination of
515 corresponding (training and test) condition in the matrix was coloured red were
516 considered as correctly classified; those for which this combination was marked (red
517 or grey) were counted to yield the total number of trials. Raw accuracy and accuracy
518 z-scores were computed as Experiment 1, while taking into account the chance level
519 ($\frac{1}{4}$ or $\frac{1}{2}$, depending on the contrast: the number of red squares divided by the number

520 of marked squares in each column). Accuracy z-scores for the “effector” vs. “goal”
521 contrast (Figure 4f) were the node-wise difference of accuracy z-scores for “effector”
522 and “goal” (Figures 4d and 4e). Surface-based group-level analyses were carried out
523 as in Experiment 1.

524

525 **Results**

526 In Experiment 2, we identified significant clusters of crossmodal action
527 information in the left hemisphere, in and around the anterior parietal cortex including
528 the postcentral gyrus. We also observed clusters bilaterally in the lateral
529 occipitotemporal cortex (Figure 7; Table 2). This result was similar when the two
530 train-test directions (train with “see” data, test with “do” data, and vice versa) were
531 examined separately (Supplementary Figure 4). Unlike Experiment 1, however, the
532 unimodal “do” but not the “see” analysis revealed areas carrying within-modality
533 information about the actions (Supplementary Figures 5 and 6).

534

535 Insert Figure 7 about here

535

536 Insert Table 2 about here

536

537

538 In order to identify regions in which the crossmodal information content was
539 biased either for action goals or for effectors, we first applied a mask to include only
540 locations for which crossmodal information, averaged across both train-test
541 directions, was significant (as in Figure 7). Each remaining vertex was coloured
542 (Figure 8) according to whether it showed stronger discrimination of: effectors (blue,
543 cyan); goals (red, yellow); or no bias (green). In the left hemisphere parietal and
544 postcentral gyrus regions, this map revealed a gradient of biases in crossmodal action
545 information. Specifically, posteriorly, similarity patterns favoured the distinction
546 between action *goals* over *effectors*. That is, the patterns for lift and punch goals were
547 less similar to each other relative to the patterns for finger and whole hand actions. In
548 contrast, moving anteriorly towards the precentral gyrus, activation patterns favoured
549 the representation of effectors. Finally, in the lateral occipitotemporal clusters, the
550 representations appeared to show no strong bias. Supplementary Figure 7 provides
551 maps showing separately areas that are biased for either the representation of goals or
552 of effectors.

553

554

Insert Figure 8 about here

555

556 **Discussion**

557 The main results of Experiment 2 were highly similar to those of Experiment
558 1, in spite of several changes to the experimental task, design, and stimuli. (Note
559 however that these differences preclude direct statistical comparisons of the two
560 experiments). We were able to achieve these results with MVPA in spite of the
561 reduced statistical power provided by an event-related design (which may nonetheless
562 have improved the psychological validity of the task). Our principal finding was that
563 patterns of activity across the dorsal and anterior parietal cortex, postcentral gyrus,
564 and lateral occipitotemporal cortex carry significant crossmodal information about
565 transitive actions. The lateral occipitotemporal regions were significant in both
566 hemispheres in both studies, suggesting a crossmodal action representation that is
567 perhaps not tied to the laterality of the specific limb used to perform the task. In
568 contrast, the parietal/postcentral clusters were largely confined to the left hemisphere.
569 It may be that the action representations identified here are specific to the hand that
570 was used to perform the actions, rather than being abstracted across the midline.
571 However, previous reports have identified left-lateralized activity in response to the
572 planning and execution of goal-directed actions performed by either the left or right
573 hand (e.g. Johnson-Frey et al., 2005). Further tests comparing left- and right-handed
574 actions will be needed to resolve questions about the laterality of the regions
575 identified here.

576 The other significant finding of Experiment 2 is that we were able to identify a
577 gradient of information content extending across the anterior parietal cortex and the
578 postcentral gyrus. This was achieved by using a factorial design that independently
579 varied the effector and the goal of the actions that were performed and observed. At
580 the posterior edge of this gradient, patterns of fMRI activity showed more information
581 about the goals of the action (lift vs punch), while towards the anterior edge, into the
582 postcentral gyrus, the bias shifted to favour the effector used to execute this action
583 (finger vs hand). Note that this pattern was observed for crossmodal analyses testing
584 the similarity of patterns across vision and action. Generally this bias is consistent
585 with previous conceptions of the postcentral gyrus as consisting of somatosensory
586 representations (closely tied to the body surface), while anterior parietal areas
587 represent actions in terms of more abstract hand-object interactions such as different

588 forms of grasp to achieve specific goals. More specifically the aIPS region in
589 particular has been implicated in object-directed grasp as opposed to reach (e.g.
590 Culham et al., 2003, Frey et al., 2005), comparable to the “lift” vs “punch” distinction
591 tested here. This finding shows that the techniques devised here have the potential to
592 reveal not only regions in which actions are coded similarly across the visual and
593 motor domains, but also to reveal more detailed information about these
594 representations.
595

General Discussion

596

597 The present results succeed in the aim to use fMRI to identify human brain
598 regions that construct, at the population level, representations of actions that cross the
599 visual and motor modalities. Specifically, we show that the distributed neural activity
600 in the regions identified here encodes both seen and performed actions in a way that is
601 at least partially unique for different actions. Thus these broad codes share an
602 essential property of macaque mirror cells – although given the grossly different
603 measures employed, any comparison between the present findings and mirror neurons
604 can only be at an abstract level.

605 Although the nature of the MVPA technique prevents pinpointing the
606 anatomical source of the crossmodal information with great precision, previous
607 findings shed some light on the neural representations that are likely to underlie the
608 crossmodal clusters identified here. The left lateral occipitotemporal region has long
609 been implicated in the understanding of action (Martin et al. 1996). Also, the clusters
610 identified here fall close to a number of functionally-defined brain regions that are
611 found bilaterally, including: the dorsal/posterior focus of the lateral occipital complex
612 (LO; Grill-Spector et al. 1999) which is involved in visual object perception; the
613 body-selective extrastriate body area (EBA; Downing et al., 2001; Peelen and
614 Downing 2007a); and motion-selective areas including proposed human homologues
615 of MT (Tootell et al. 1995) and MST (Huk et al. 2002). Accordingly it is difficult to
616 assess which of these neural populations, if any, may contribute to the crossmodal
617 information identified here. For example, area MST, which responds to both visual
618 motion and tactile stimulation (Beauchamp et al. 2007), may carry neural responses
619 that are crossmodally informative about actions. Further, EBA has been proposed to
620 have a role in the guidance of unseen motor behaviour and even to play a part in the
621 human mirror “network”, and hence might play a crossmodal role in action
622 representation (Astafiev et al. 2004; Jackson et al. 2006; but see Candidi et al., 2008;
623 Kontaris et al. 2009; Peelen and Downing 2005; Urgesi et al., 2007).

624 Many findings converge on the idea that the parietal cortex generally codes
625 aspects both of the position of the body and its movements, and of visual information,
626 particularly regarding stimuli that are the targets of action. In human neuroimaging
627 studies, activations in the general region of aIPS have frequently been identified in
628 tasks involving either executing or observing human actions, typically those that are
629 object-directed (Tunik et al. 2007; Van Overwalle and Baetens 2009). Evidence of

630 this kind has led some researchers to the conclusion that this region is part of a human
631 mirror system, although recent work with adaptation and MVPA methods has not
632 supported this hypothesis (Dinstein et al. 2007, 2008a). The present results provide
633 positive evidence for anterior parietal cortex carrying a genuinely crossmodal action
634 code.

635 The left parietal crossmodal clusters extend substantially into the postcentral
636 gyrus, implicating a role for somatosensory representations in the visual/motor
637 representation of actions. This pattern was especially apparent in Experiment 2, which
638 (unlike Experiment 1) required finely controlled actions as the hand interacted with
639 the object in different ways. Previous work has shown somatosensory activation by
640 seeing others reach for and manipulate objects (e.g. Avikainen et al. 2002;
641 Cunnington et al. 2006), as well as during passive touch (e.g., Keysers et al. 2004).
642 The role of somatosensation in representing sensory aspects during haptic object
643 exploration (e.g., Miquee et al. 2008) suggests its role in action simulation during
644 observation is based on the sensory-tactile aspects of skin-object interactions (e.g.,
645 Gazzola and Keysers 2009; see also Keysers et al., 2010).

646 In Experiment 2 we tested the hypothesis that meaningful, object-directed
647 actions would be more effective than intransitive actions in engaging the ventral
648 premotor cortex (PMv), as found in previous single-unit studies of the macaque and in
649 univariate fMRI studies of the human (e.g., Rizzolatti et al. 1996a, b, 2001). This
650 hypothesis was not confirmed, and indeed in neither experiment did we find
651 significant crossmodal information in PMv. Previous evidence for common coding of
652 vision and action in human PMv was based on overlapping activations in univariate
653 analyses, and as noted above, this could be due to separate but overlapping neural
654 codes for visual and motor action properties in the same brain region.

655 On its face, however, that argument is not consistent with the findings of
656 Kilner et al. (2009), who found adaptation in PMv from vision to action and vice
657 versa. Note, however, that the visual stimuli in Kilner et al (2009) were depicted from
658 an egocentric view that matched the participant's own viewpoint, rather than the
659 typical view seen of another person's actions. In contrast, in our study the visual
660 stimuli were clearly views of another person's actions. Further studies should test
661 whether MVPA approaches detect crossmodal action information in PMv when the
662 visually-presented actions are seen egocentrically (and also whether adaptation effects
663 are found when actions are presented allocentrically). If MVPA and adaptation effects

664 in PMv are found only for egocentric views, this would limit the proposed homology
665 between BOLD activity in this region in humans and single-cell findings in the
666 macaque.

667 Setting aside the above considerations, it could of course be the case that
668 crossmodal visual/motor action properties are represented jointly in human PMv from
669 any viewing perspective, but on a spatial scale that is not well matched by the
670 combination of imaging resolution and MVPA methods adopted here (cf. Swisher et
671 al., 2010). It is difficult to draw conclusions from a null effect, and we do not take the
672 absence of significant clusters in PMv (and other) regions in the present study as
673 strong evidence against the presence of crossmodal visual-motor representations in
674 those regions.

675 As reviewed in the Introduction, recent evidence on visual/motor action
676 representations from repetition-suppression methods is mixed. One possible
677 hypothesis is that the relevant neural populations may not adapt in the same way as do
678 neurons in other regions such as visual cortex. Previous single-cell studies in
679 macaques support this proposal. For example, Leinonen et al. (1979) measured neural
680 activity in aIPS, noting that “Cells that responded to palpation or joint movement
681 showed no marked habituation on repetitive stimulation”. Similarly, Gallese et al.
682 (1996) mentioned that for mirror neurons in frontal area F5, “[t]he visual stimuli most
683 effective in triggering mirror neurons were actions in which the experimenter’s hand
684 or mouth interacted with objects. The responses evoked by these stimuli were highly
685 consistent and did not habituate”.

686 However, several imaging adaptation studies have shown within-modality
687 adaptation effects, and/or unidirectional cross-modal adaptation (Chong et al. 2008;
688 Hamilton and Grafton 2006). In some cases (e.g. Chong et al. 2008), this could reflect
689 adaptation of semantic representations instead of (or in addition to) visuo-motor
690 representations, although in other paradigms this possibility can be ruled out (Lingnau
691 et al. 2009). Most recently, as noted above, Kilner et al. (2009) have shown fully
692 crossmodal adaptation effects.

693 A potentially important consideration is that the repetition suppression studies
694 to date have focused on short-term repetition, which relates in uncertain and
695 potentially complex ways to single-unit spiking activity (Sawamura et al. 2006) and to
696 long-term priming (Epstein et al. 2008). This emphasis on the short-term changes in
697 activity resulting from repetition stands in contrast to the present approach of

698 identifying those aspects of activation patterns that remain constant over relatively
699 long time scales on the order of tens of minutes. Clearly, further studies will need to
700 directly compare MVPA and adaptation measures (both short-term and long-term) of
701 crossmodal action representations.

702 As noted above, there have been previous attempts to identify crossmodal
703 visual/motor action representations with MVPA, most notably by Dinstein et al.
704 (2008a). That study used an event-related fMRI paradigm and a “rock-paper-scissors”
705 task, in which participants freely chose to perform one of three actions on each trial in
706 a simulated competition against a computer opponent. MVPA revealed that activity in
707 left and right aIPS could discriminate, within-modality, among both perceived and
708 performed actions, but in contrast to the present findings this did not extend to the
709 crossmodal case. While there are some similarities between Dinstein et al (2008a) and
710 the present study that can be excluded as causing the divergent results (e.g. both used
711 similar linear discriminant analysis classifiers; both tested hand movements), there are
712 several differences between the approaches used. For one, Dinstein et al (2008a) used
713 functionally-defined regions of interest and so may have missed areas that do not
714 necessarily exhibit strong responses in the univariate sense (see below). Alternatively,
715 task characteristics may be important. The “rock-paper-scissors” task has the
716 advantage over other paradigms that participants freely choose their own actions to
717 perform. However, in it, actions are also performed in a competitive context, which
718 may alter or inhibit representations of the opponent’s actions.

719 Our findings underscore the benefits of whole-brain analyses for MVPA. The
720 use of standardized coordinates does not take into account inter-subject variability in
721 the anatomical structure of the brain, while the using functional localisers to identify *a*
722 *priori* regions of interest relies on the assumption that higher gross activation levels
723 (e.g., for doing and seeing actions) in a region are a necessary condition for
724 identifying representations of individual actions in that region. Our novel combination
725 of surface reconstruction and information mapping (Oosterhof et al., in press)
726 provides a data-driven map for the whole brain, featuring voxel selection and inter-
727 participant alignment that respect cortical anatomy (Fischl et al. 1999). In this way we
728 have identified areas of potential interest – specifically the lateral occipitotemporal
729 cortex – that were not examined by previous studies of crossmodal visual/motor
730 action representation.

731 Finally, one general issue that must be confronted is that of mental imagery. It
732 is possible in principle that areas that appear to carry crossmodal vision/action
733 information are actually unimodal, with the additional assumption that one type of
734 task (e.g. performing actions) elicits imagery in another modality (e.g. visual imagery
735 for actions) that is highly similar to a real-world percept (e.g. seeing actions
736 performed). Indeed, studies that explicitly compare actual performance and imagined
737 performance of actions do find overlapping areas of brain activity (e.g. in parietal
738 cortex; Filimon et al., 2007; Lui et al., 2008). This issue is not only relevant to the
739 present work but also to a wide range of previous studies on action perception /
740 performance. Indeed it could apply still more generally across other studies of
741 multimodal cognition: for example, brain areas active for reading words, or for
742 hearing meaningful sounds, or for tactile perception of textures could all in principle
743 reflect visual imagery for their referent objects. The present study does not resolve
744 this question. One avenue for future research would be to adapt the methods used here
745 to test for crossmodal action representations when visual action depictions are
746 presented under conditions of divided attention (which would presumably make
747 imagery more difficult) or even under subliminal conditions (which would make it
748 impossible).

749

750 **Conclusion**

751 The present results open the way for future studies using MVPA to explore
752 the neural “space” of action representation. Furthermore, the approach developed here
753 could be adopted to test the boundaries of cross-modal action matching. For example,
754 the preceding discussion raised a question about the extent to which the neural
755 activity patterns elicited by observing actions is modulated by variations in viewpoint
756 (cf. Vogt et al. 2003). Additionally, we can ask what role attention and task set play in
757 the construction of crossmodal action representations (cf. Reddy et al., 2009;
758 Esterman et al., 2009). Finally, combining transcranial magnetic stimulation with
759 fMRI would open the possibility of disrupting information-bearing areas, such as
760 those identified here, in order to assess the consequent effects on behaviour and on
761 remote, interconnected brain regions.

762

763

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Figure Captions

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1. Schematic illustration of the trial structure in Experiment 1. Each block began with a warning signal, followed by a 1.5 s movie showing one of three simple, intransitive manual actions. A task cue (“see” or “do”) and a blank interval then followed. On “see” trials, the same movie was then presented eight times in succession, with a 0.5 sec blank interval between each movie presentation. On “do” trials, a central fixation dot grew larger for 1.5 sec and then shrank again for 0.5 sec, in a cycle that repeated eight times and that was matched to the cycle of movie presentations in the “see” condition. In the “do” condition, participants were required to perform the action that had appeared at the start of the block, in synchrony with the expansion of the fixation point.

2. Comparison of voxel selection methods in information mapping. (a) Schematic representation of a brain slice, with white matter, grey matter, and matter outside the brain indicated. The curved lines represent the white matter/grey matter boundary, the grey matter/pial surface boundary, and the skull. With the traditional volume-based voxel selection method for multivoxel pattern analysis, a voxel (blue) is taken as the center of a sphere (red; represented by a circle), and all voxels within the sphere are selected for further pattern analysis. (b) An improvement over (a), in that only grey matter voxels are selected. The grey matter can either be defined using a probability map, or using cortical surface reconstruction. A limitation however is that voxels close in Euclidian distance but far in geodesic distance (i.e. measured along the cortical surface) are included in the selection, as illustrated by the three voxels on the left. (c) Using surface reconstruction, the white matter-grey matter and grey matter-pial surfaces are averaged, resulting in an intermediate surface that is used to measure geodesic distances. A node on the intermediate surface (blue) is taken as the center of a circle (red; represented by a solid line), the corresponding circles on the white-grey matter and grey matter-pial surfaces are constructed (red dashed lines), and only voxels in between these two circles are selected.

3. Group crossmodal surface information map for Experiment 1, generated using multivoxel pattern analysis with an LDA classifier with training and test data from different (“see” vs. “do”) modalities. (a) The coloured brain clusters (see Table 1)

999 indicate vertices where grey matter voxels within the surrounding circle on the
1000 cortical surface show above-chance crossmodal information (random effects analysis,
1001 thresholded for cluster size). Crossmodal visuo-motor information about intransitive
1002 manual actions is found in the left hemisphere at the junction of the intraparietal and
1003 postcentral sulci, and bilaterally in lateral occipitotemporal cortex. For each node this
1004 is based on two classifications, in which either the data from the “see” condition was
1005 used to train the classifier and the data from the “do” condition was used as test data,
1006 or vice versa. Insets: detailed view of the significant clusters. **(b)** The same map as
1007 (a), but without cluster thresholding. The color map legend (bottom left) shows the t-
1008 value of the group analysis against chance accuracy for panels (a) and (b). **(c)** As (a),
1009 except that mean classification accuracy values (chance = 33.3%) are depicted. **(d)** As
1010 (c), without cluster thresholding. The color map legend (bottom right) shows the
1011 accuracy scale for panels (c) and (d). Abbreviations: CS, central sulcus; PoCS, post-
1012 central sulcus; IPS, intraparietal sulcus; STS, superior temporal sulcus.

1013

1014 **4.** Similarity matrices for evaluation of Experiment 2 cross-validation classification
1015 results. Each row and each column (for training set and test set, respectively)
1016 represents one of the eight conditions in the experiment, formed by the combination
1017 of modality (see, do) x effector (finger, hand) x goal (lift, punch). Where fMRI
1018 activity patterns are predicted to be similar (across training and test set, for a given
1019 brain region and a given participant), a cell matrix is marked with a pink square.
1020 Conversely, trials that were used in the cross-validation scheme but where no
1021 similarity between patterns is predicted, are indicated with a grey square. **(a)** This
1022 example represents predicted similarity for within-modality “do” action representation.
1023 The fMRI activity patterns elicited by performing a given action are predicted to be
1024 similar across multiple executions of that action, compared to a different action. **(b,c)**
1025 Similarity matrices for within-modality “see” and cross-modal action representation.
1026 In the crossmodal case (c), the prediction is that the fMRI activity pattern elicited by
1027 performing a given action will be similar to that elicited by seeing that action (relative
1028 to other actions), and *vice versa*. **(d,e)**. Similarity matrices for representation of goal
1029 irrespective of effector, and vice versa. Note that both cases reflect information
1030 carried across modalities. **(f)** Similarity matrix for the contrast of goal vs. effector,
1031 where blue squares indicate similarity of patterns, but with a negative weight. Note
1032 that this matrix is the difference between the matrices in (d) and (e). Also note that the

1033 matrices in (a-c) are equally applicable to Experiment 1, but with three actions in each
1034 modality instead of four.

1035

1036 **5.** Experimental stimuli from Experiment 2. **(a)** Frame capture from video recording
1037 during Experiment 2, showing the position of the participant's hand, experimenter's
1038 hand, and the target object during a null (no action) trial. **(b)** Similar to (a), but the
1039 experimenter performs a "punch hand" action that is observed by the participant. **(c)**
1040 Frames illustrating each of the four actions used in the experiment, formed by
1041 crossing effector (finger, hand) with goal (lift, punch).

1042

1043 **6.** Schematic of the trial structure for Experiment 2. The top row shows the series of
1044 events in "see" trials, and the bottom row events in "do" trials.

1045

1046 **7.** Group crossmodal surface information map for Experiment 2. **(a)** Cluster-
1047 thresholded map (conventions as in Figure 3) of crossmodal visuo-motor information
1048 about transitive manual actions is found in the left hemisphere, around the junction of
1049 the intraparietal and postcentral sulci, and in lateral occipitotemporal cortex bilaterally
1050 (see Table 2). **(b)** The same map as (a), without cluster thresholding. The color map
1051 legend (bottom left) shows the t-value of the group analysis against chance accuracy
1052 for panels (a) and (b). **(c)** As (a), except that mean classification accuracy values
1053 (chance = 25%) are depicted. **(d)** As (c), without cluster thresholding. The color map
1054 legend (bottom right) shows the accuracy scale for panels (c) and (d). Abbreviations:
1055 CS, central sulcus; PoCS, post-central sulcus; IPS, intraparietal sulcus; STS, superior
1056 temporal sulcus.

1057

1058 **8.** Regions in which representations are biased for effector or goal, Experiment 2.
1059 These data were first masked to select regions for which accuracy in the overall
1060 crossmodal analysis (Figure 7) was above chance. Vertices are coloured to indicate a
1061 bias in favour of either discrimination of the action effector (blue / cyan) or
1062 discrimination of the action goal (red / yellow). Areas with no bias are shown in
1063 green. Note a gradient in the bias from effector (postcentral gyrus) to action (superior
1064 parietal cortex).

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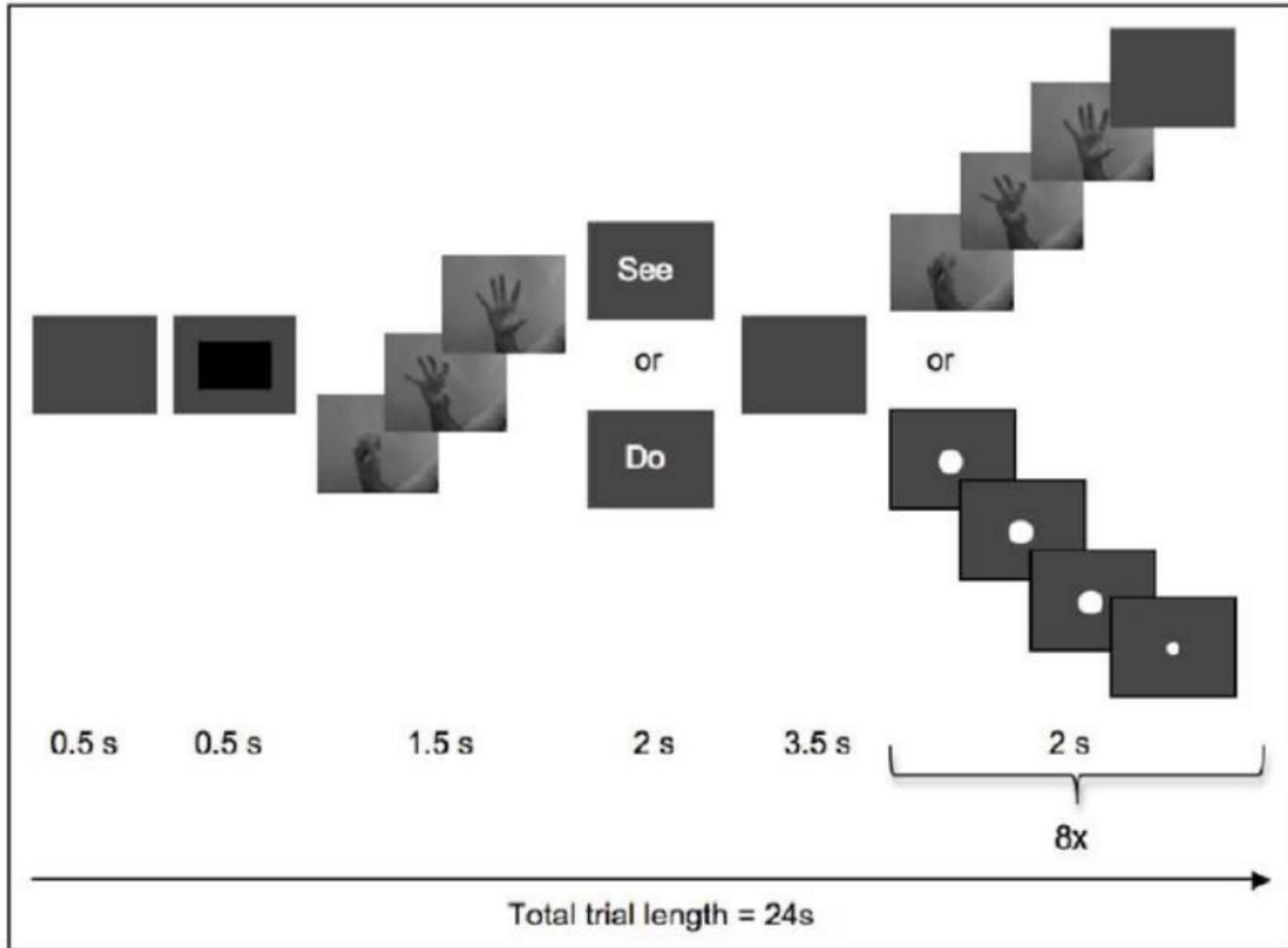
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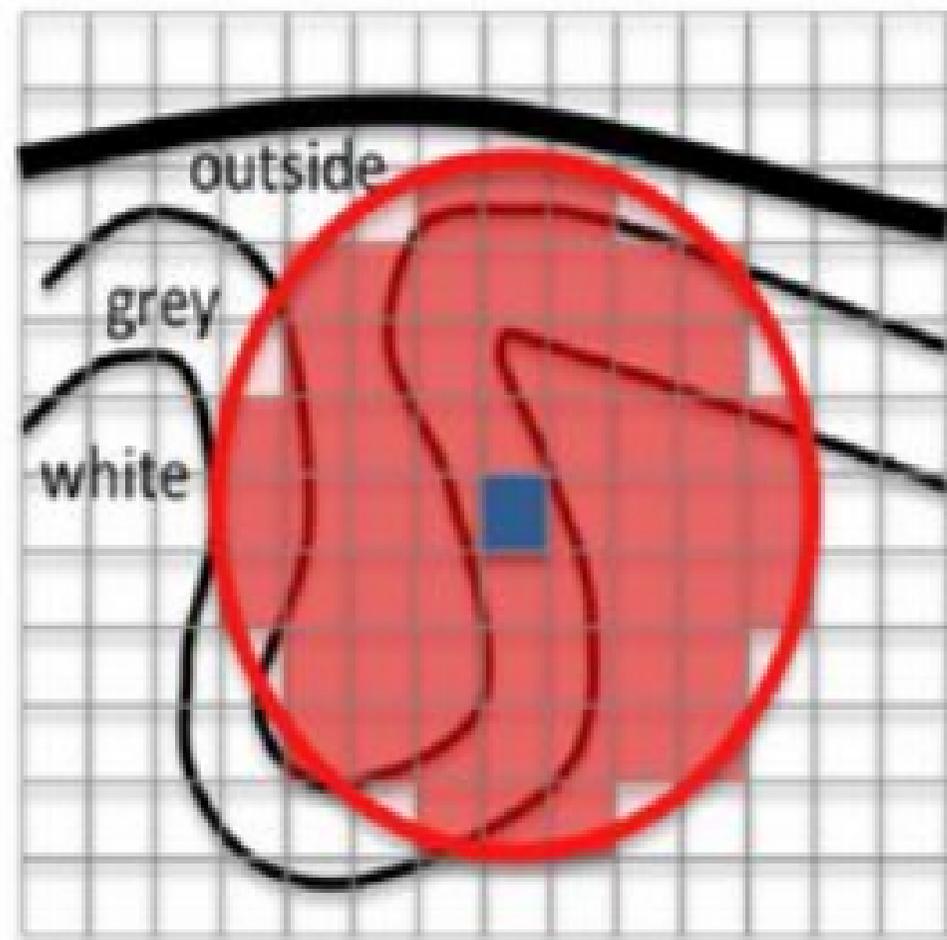
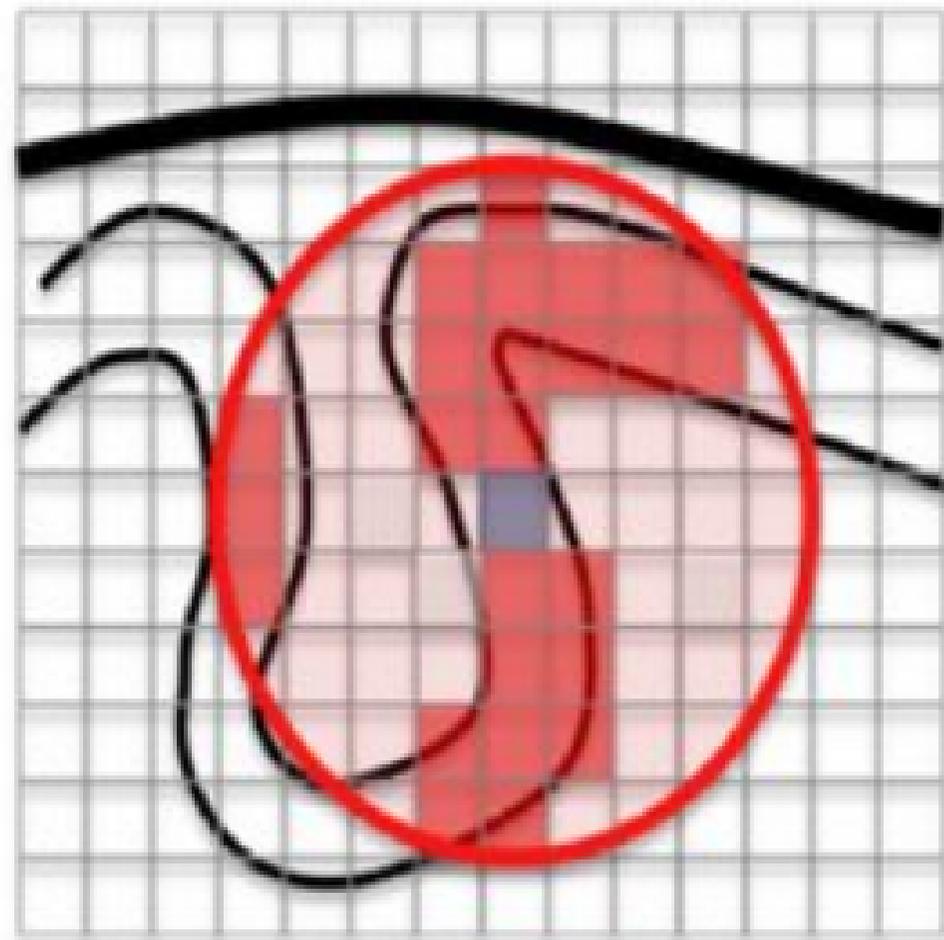
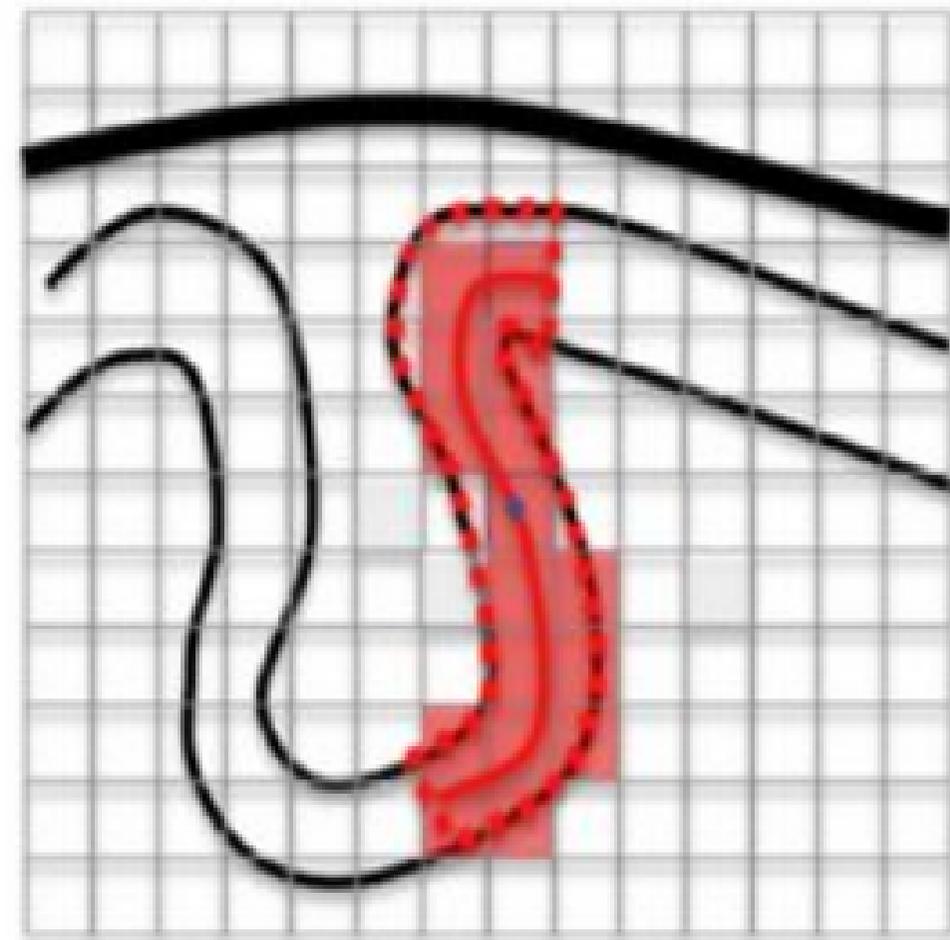
Table 1. Significant clusters in Experiment 1 that carry cross-modal information (see Figure 3). Center of mass is shown in Talairach coordinates. Mean and maximum classification t-values within each cluster are shown. Clusters are thresholded based on a bootstrap-approach (see Methods). Approximate anatomical locations are provided. Abbreviations: IPS, intraparietal sulcus; OT, occipitotemporal cortex; EVC, early visual cortex; MTG, middle temporal gyrus

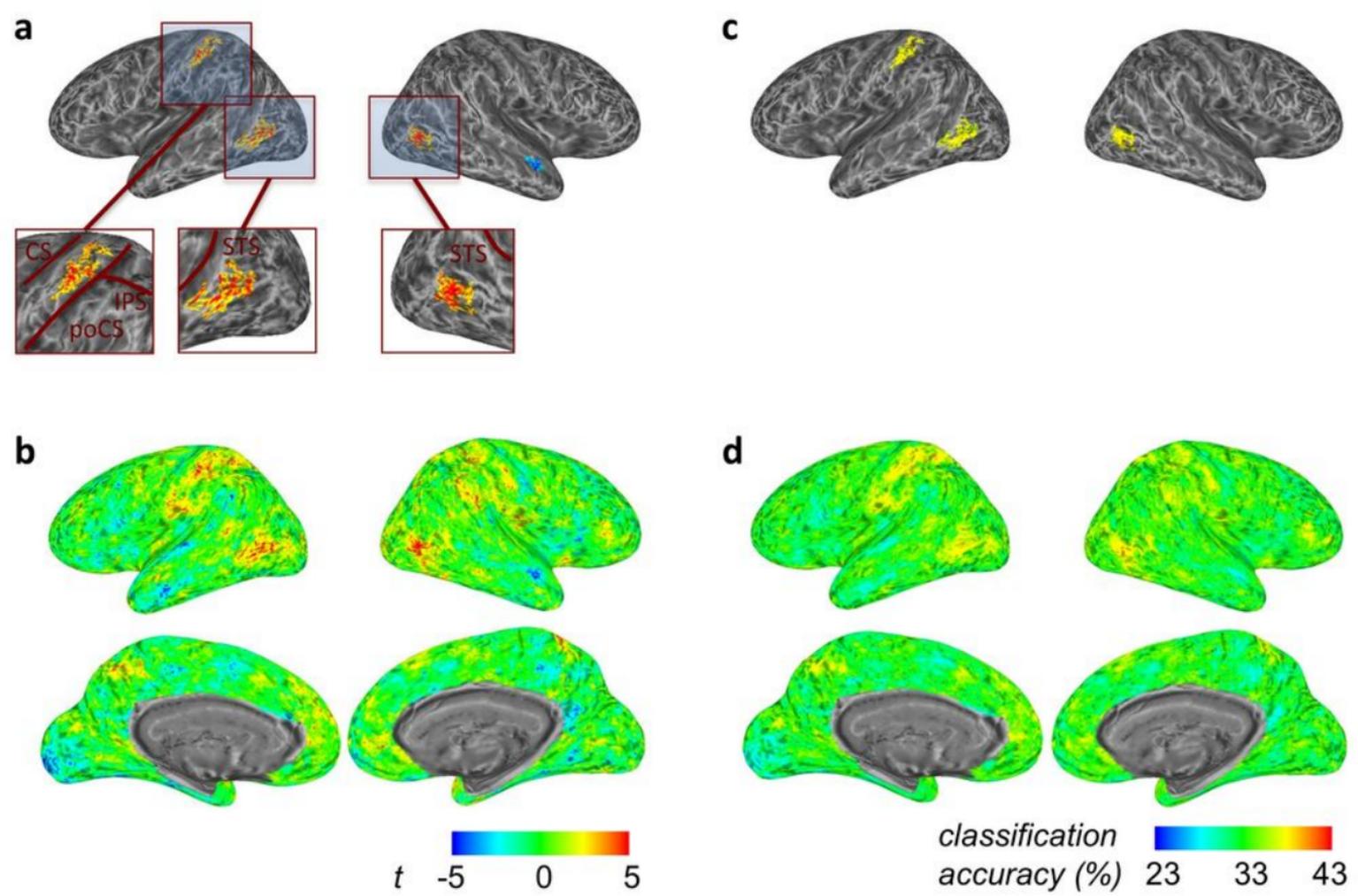
Name	Area (mm ²)	CoM L-R	CoM P-A	CoM I-S	Mean	Max
Left hemisphere						
aIPS	493	-44	-32	47	3.52	10.02
OT	445	-53	-56	3	3.72	9.71
EVC	329	-9	-87	-1	-3.79	-2.45
Right hemisphere						
aIPS	303	45	-62	3	3.89	11.11
MTG	87	48	-7	-10	-3.92	-2.46

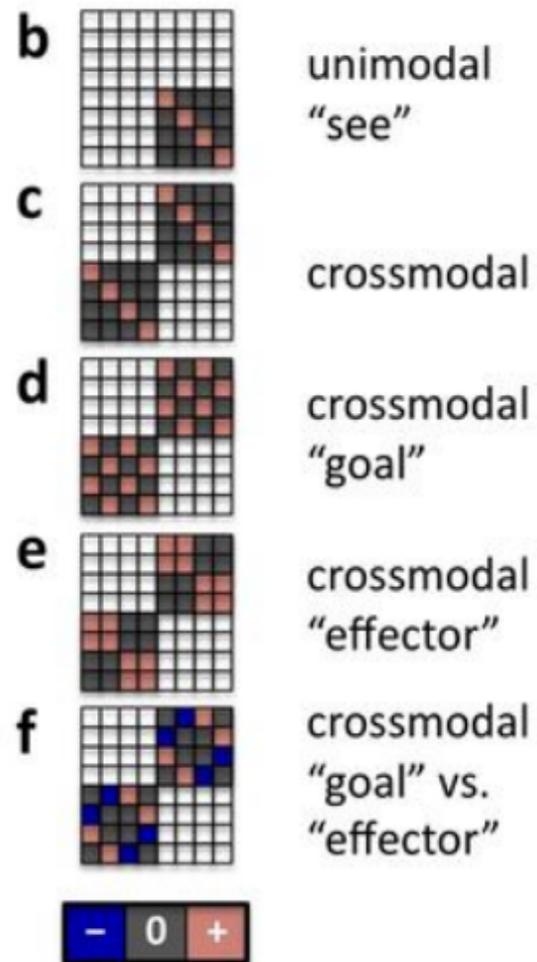
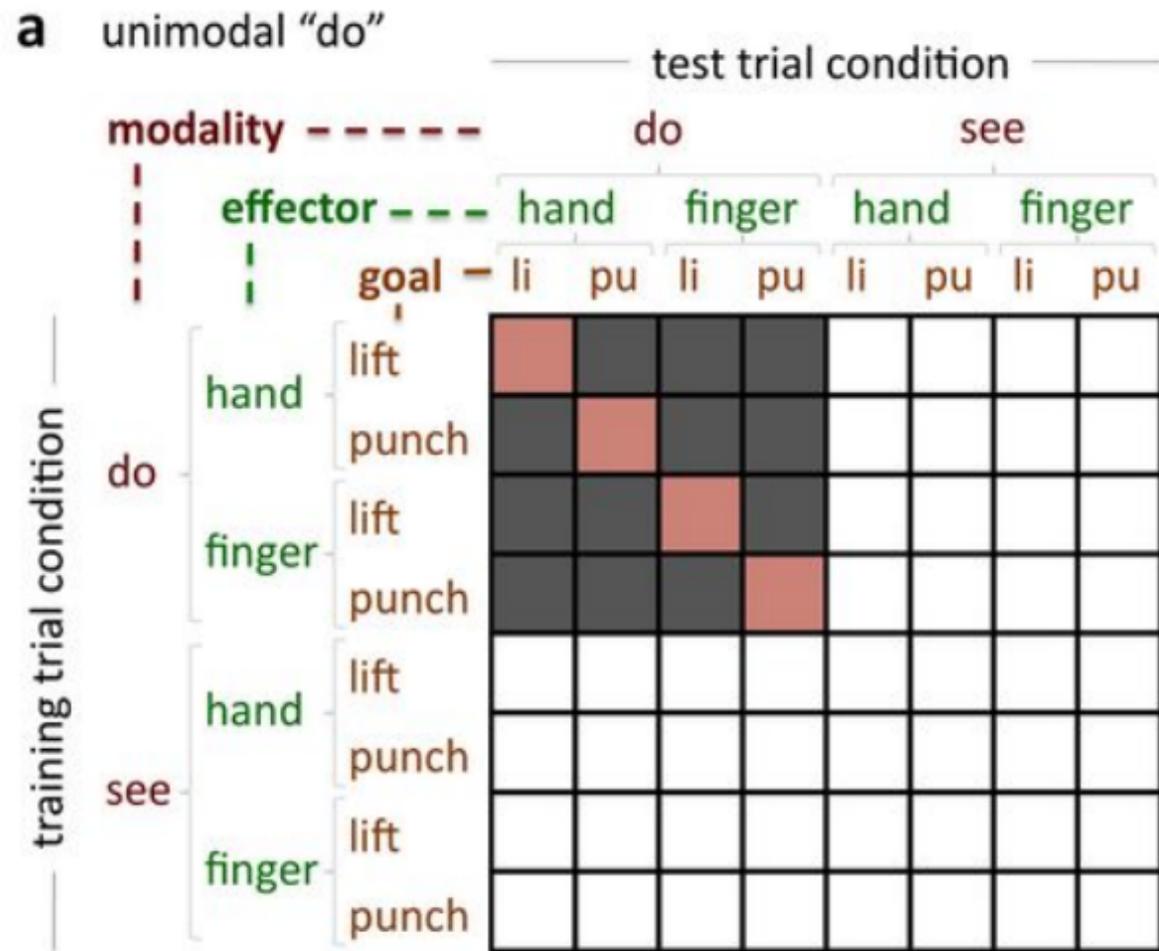
Table 2. Significant clusters in Experiment 2 that carry cross-modal information (see Figure 7). Conventions as in Table 1. Abbreviations: IPS, intraparietal sulcus; OT, occipitotemporal cortex; poCG, postcentral gyrus; SFG, superior frontal gyrus; PCC, posterior cingulate cortex.

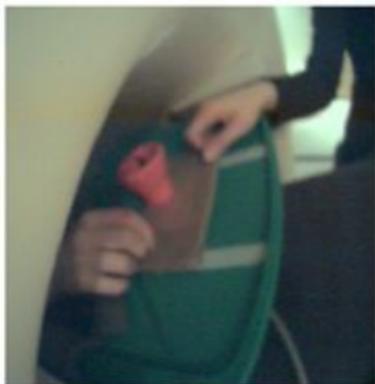
Name	Area (mm ²)	CoM L-R	CoM P-A	CoM I-S	Mean	Max
Left hemisphere						
aIPS	1953	-44	-31	44	3.38	7.61
OT	749	-49	-61	2	3.72	9.60
poCG	532	-52	-19	20	2.80	5.10
SFG	142	-23	54	12	-2.94	-2.20
Right hemisphere						
OT	887	43	-61	-7	3.14	7.59
PCC	217	5	-56	19	-3.19	-2.20



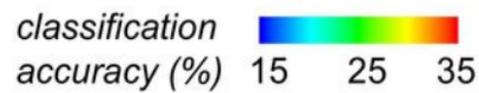
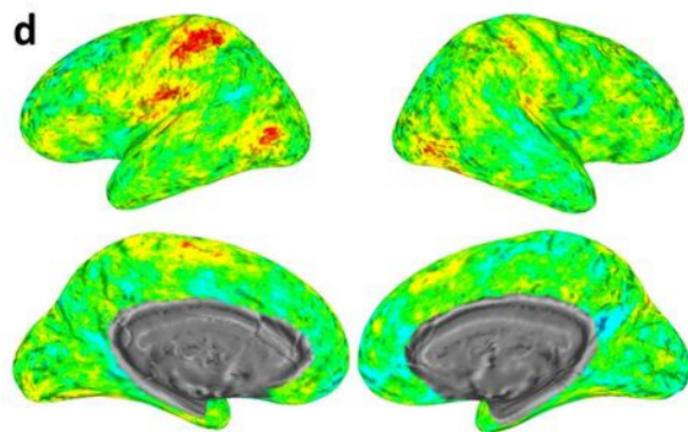
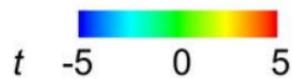
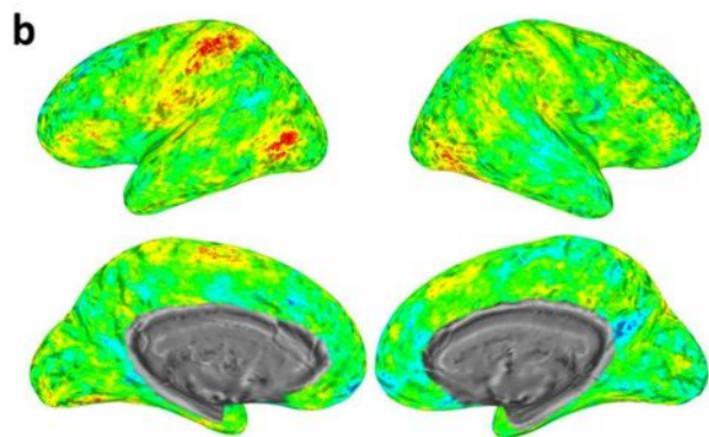
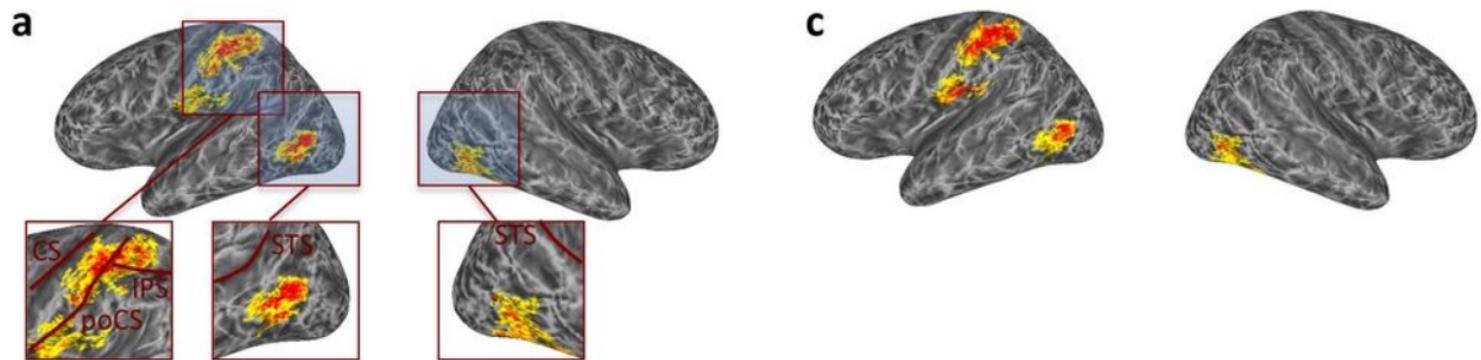
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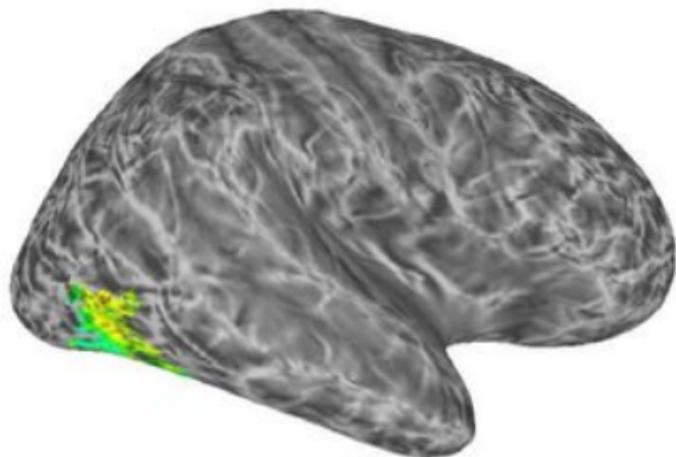
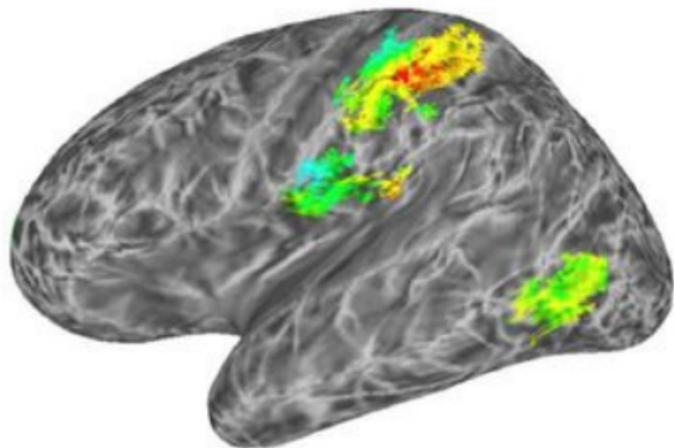




a**b****c***i**ii**iii**iv*

“see” trials	instruction	“open”	
	action	(opens eyes)	(observes experimenter executing action)
		or	
“do” trials	instruction	“close”	“punch hand”
	action	(closes eyes)	(executes action)
		2 s	5 s





bias

effector

goal



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